

NEW! Updated schedule. For organizational reasons some presentations have been moved to a different time slot within the same session.

TueCVT7: Motion and Path Planning IV

	Original Schedule	Updated Schedule
“Spatially Targeted Communication and Self-Assembly” , Nithin Mathews, Anders Lyhne Christensen, Rehan O'Grady*, Marco Dorigo	TueCVT7.4 15:45-15:50	TueCVT7.6 15:55 -16:00
“Fighting Fires with Human Robot Teams” , Eric Martinson*, Wallace Lawson, Samuel Blisard, Anthony Harrison, Greg Trafton	TueCVT7.6 15:55 -16:00	TueCVT7.4 15:45-15:50

WedCT1: Object Detection and Tracking

	Original Schedule	Updated Schedule
“Exploiting and Modeling Local 3D Structure for Predicting Object Locations” , Alper Aydemir*, Patric Jensfelt	WedCT1.3 11:30 - 11:45	WedCT1.1 11:00 - 11:15
“Reliable Object Detection and Segmentation using Inpainting” , Ji Hoon Joung*, Michael S. Ryoo, Sunglok Choi, Sung Rak Kim	WedCT1.1 11:00 - 11:15	WedCT1.3 11:30 - 11:45

WedET1: Ominidirectional Vision and Aerial Robotics II

	Original Schedule	Updated Schedule
“Vision-Based Autonomous Mapping and Exploration Using a Quadrotor MAV” , Friedrich Fraundorfer, Lionel Heng*, Dominik Honegger, Gim Hee Lee, Lorenz Meier, Petri Tanskanen, Marc Pollefeys	WedET1.3 15:30-15:45	WedET1.1 15:00-15:15
“Vision-only estimation of wind field strength and direction from an aerial platform”, Richard James Donald Moore*, Saul Thurrowgood, Mandyam Srinivasan	WedET1.1 15:00 - 15:15	WedET1.3 15:30 - 15:45